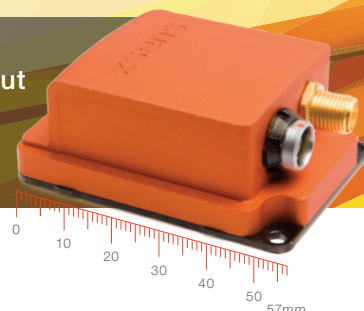




MTi-G-710

Turnkey GNSS/INS solution for navigation and stabilization applications

- ✓ All-in-one sensor system with high-frequency position and orientation output
- ✓ Excellent heading tracking without requiring a magnetic field
- ✓ Configurable output settings, synchronizes with any 3rd party device



Complete Xsens sensor fusion algorithm

- Compensation against long-lasting transient accelerations
- Ability to cope with GNSS outages
- Non-magnetic heading reference
- Active Heading Stabilization (AHS) for continuous accuracy in heading tracking
- Tuned for performance under vibrations
- Selectable filter profiles for range of applications

Best-in-class hardware design

- Highest quality industrial grade components
- Vibration-rejecting gyroscopes and accelerometers
- Built-in multi-GNSS receiver (GPS, GLONASS, BeiDou, Galileo) and barometer
- Wide array of (time) synchronization options

Easy software integration

- Extensive suite of configurable output formats, calculated onboard the MTi-G-710
- MT Software Suite with intuitive GUI
- Complete SDK for all operating systems
- Support for Robotic Operating System (ROS)
- Xsens Xbus protocol or ASCII (NMEA)
- Access to BASE (by Xsens), an extensive knowledge base and community forum

Specification highlights

- True North without requiring a magnetic field
- IP67 encased version or OEM board
- Choice of several interfaces and onboard USB
- All Xsens products are fully interchangeable
- Cost-effective system integrator solution
- Position, velocity and orientation outputs

Product overview

MTi-G-710 GNSS/INS		
Typ Max		
Calibrated Sensor Data		
yes		
Roll/pitch	Static	0.2° 0.25°
	Dynamic	0.3° 1.0°
Yaw	In homogenous magnetic field	1.0°
Position and velocity		
Horizontal position	1 σ STD (SBAS)	1.0 m
Vertical position	1 σ STD (SBAS, baro)	2.0 m
Velocity	1 σ RMS	0.05 m/s

Sensor specification

	Gyroscopes	Accelerometers
Standard full range	+/- 450 °/s	+/- 20 g
Initial bias error	0.2 °/s	5 mg
In-run bias stability	10 °/h	15 µg
Bandwidth (-3 dB)	415 Hz	375 Hz
Noise density	0.01 °/s/√Hz	60 µg/√Hz
g-sensitivity (calibrated)	0.003 °/s/g	N/A
Non-orthogonality	0.05 deg	0.05 deg
Non-linearity	0.01%	0.1%
	Magnetometer	Barometer
Standard full range	+/- 8 G	300-1100 hPa
Total RMS noise	0.5 mG	3.6 Pa
Non-linearity	0.2%	N/A
Resolution	0.25 mG	8cm (sea level, 15 °C)
	GNSS receiver	
Receiver type	72ch with SBAS; GPS, QZSS, Galileo, GLONASS, BeiDou	Horizontal accuracy (CEP) 2.0 m 2.5 m w/o SBAS
Start-up time cold start	26 s	Vertical accuracy (CEP) 5 m
Tracking sensitivity	-167 dBm	Velocity accuracy (@30 m/s) 0.05 m/s

System specifications

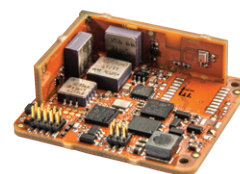
Input voltage	4.5 to 34V or 3V3	Output frequency	Up to 2 kHz
Typical power consumption	750 mW @ 5V	Interfaces	RS232/RS422/RS485/USB UART
IP-rating	IP67 (encased)	Latency	<2 ms
Temperature (in use)	-40 to 85 °C	Clock drift	1 ppm or external reference
Vibration and shock	MIL STD-202 / 2000g	Interface protocol	Xbus or ASCII (NMEA)
Sampling frequency	10 kHz/ch (60kS/s)	MTBF	300,000 hours
Sync options	SyncIn, SyncOut, Clock sync 1 PPS	Mounting orientation	Orientation alignment in firmware



MTi-G-710 Development Kit:
MTi-G-710, antenna, software
and cabling



MTi-G-710 encased:
57x42x23.5 mm, 55g,
9-pins push-pull connector



MTi-G-710 OEM:
37x33x12 mm, 11g,
16-pins header